

Hardware-defined Software: Concepts & Architecture

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1. HW/SW and SW/SW basic dependencies

- 1.SW Taxonomies
- 2.Case studies
- 3.Basic SW Dependencies Conclusions

2. Layered Hardware-dependant-Software

- 1.Introduction to HdS Stack
- 2.Linux
- 3.WinCE
- 4.HdS Stack Conclusion

3. IP Xact & HdS

Lets Focus on Binary...

- SW IP can be delivered in source or binary form
 - Source code is more abstract – Source code is actually a mean to shield from some hardware dependencies
 - Binary only delivery won't go away anyway: binary-only-deliveries, specialized compute intensive code, etc
 - In this part of the talk, software will mean binary software
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What a piece of software does vs. what a piece of software is

- Software for what it does. Keywords are
 - Signal processing, Video compression, Codecs, Baseband radio, UMTS layers, CRC algorithms, etc.
- Software for what it is. Keywords are
 - ARM binary, Libraries, intel ABI, POSIX API, Instruction Set, x86 IS, DSP IS, VxWorks, eCos, etc.

SW for « What it does »

- Provides a business function taxonomy
 - FFT, IFFT, CRC, dithering, etc.
- Provides relevant information to build systems from functions
- Answers the question
 - What function do I have to write/reuse/buy to develop my application?

- Details the dependencies of (binary) software towards
 - Hardware
 - Processor: instruction set, register set
 - Memory: Memory map, cache sizes & parameters
 - IP: registers banks, interruption
 - Software
 - Compiler tool chain: ABI (appl. binary interface)
 - Other software: API (appl. programming interface)
 - Operating system:
 - Driver framework
 - Basis for assembly rules of SW dedicated on a given hardware
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Structure Before Business

- IP-Xact is all about structural description of HW IP
 - So should be its extensions for software
 - We need first to express the necessary information required to decide if and how software can be assembled
 - That's structural description of software
 - Such description are mute about the business functions implemented by a piece of software
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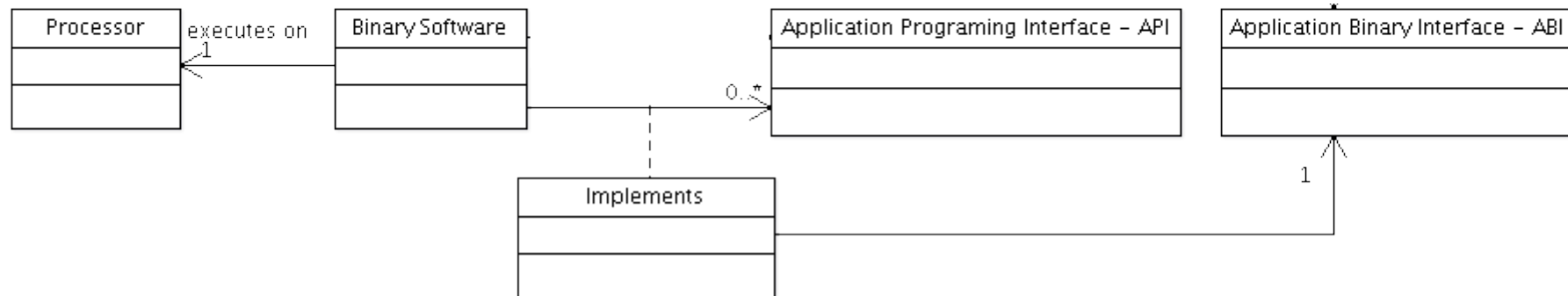
4. HdS Stack Conclusion

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A Simple Software IP (1/2): User Documentation

- Software that compute $\cos(x)$
 - The software exported API is named “mycosine.h”
 - Exports a single function “double mycosine(double);”
- The SW IP
 - Is named “mycosine”
 - Is compiled for ia32 with SSE instructions

A Simple Software IP (2/2): Detailed Dependencies



- Dependency towards the processor
 - Requires a ia32 processor with SSE instructions
- Dependency towards the calling protocol
 - Export its API through ABI v3.3 of GCC for ia32
- Dependency towards API descriptions
 - Is an implementation of “mycosine.h”

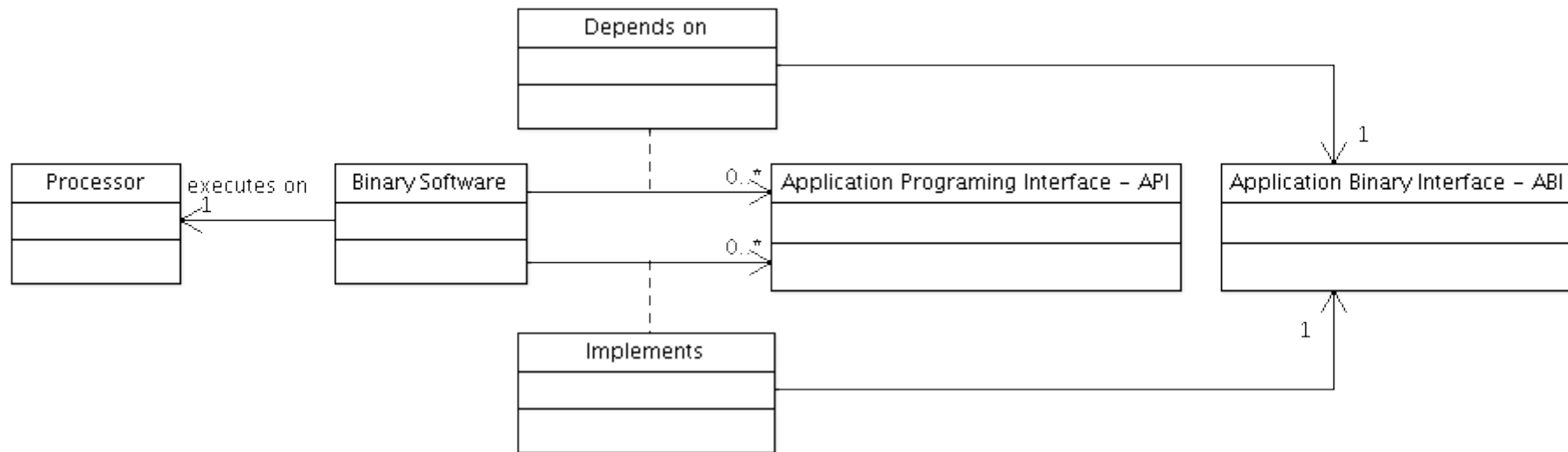


SOFTSOC Another Simple Software IP (1/2): User Documentation

- The software exported API
 - Is named “myfft.h”
 - Exports a single function
“double[] myfft(double[], size_t n);”
 - The software binary implementation
 - Is named “myfft”
 - Requires another SW IP
 - mycosine
 - Is compiled for ia32 with SSE instructions
-



Another Simple Software IP (2/2): Detailed Dependencies



- Dependency towards the processor
 - Requires a ia32 processor with SSE instructions
- Dependency towards the calling protocol
 - Obeys ABI v3.3 of GCC for ia32
- Dependency towards API descriptions
 - Is an implementation of "my-fft.h"
- Depends on "my-cosine"

- A never-ending countdown (9 to 0) made of
 - Hardware
 - A 386 processor
 - A HW IP: 7 segment decoder for LCD display
 - Named “7-seg-lcd-decoder”
 - Exports a single 8 bit register with bits 0-6 writeable
 - The register is mapped at 0x00000140
 - Software
 - Closed software
 - No operating system
 - No RTC: Calibrated software loops
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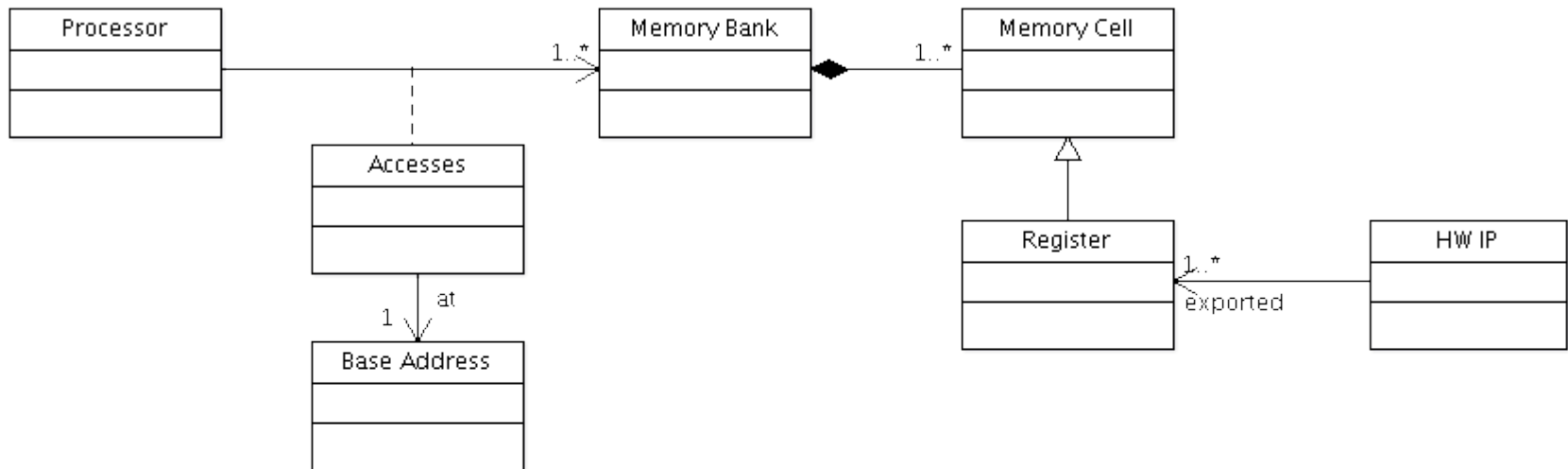
- Dependency towards the processor
 - Requires a ia32 processor
 - Dependency towards the calling protocol
 - Obeys ia32 ABI v3.3
 - Dependency towards API descriptions
 - <none>
 - **Dependency towards the HW IP**
 - One instance of hardware IP “7-seg-lcd-decoder”
 - The memory map has it at 0x00000140
-

HW IP-dependent SW IP (3/3): More Detailed Dependencies

- “One instance 7-seg-lcd-decoder”, means :
 - The SW IP shall drive the IP through registers whose format is defined by the IP
 - “The memory map has the decoder at 0x0140”
 - The register is memory mapped
 - The SW IP code shall have the rights to access it
 - Its address is known and constant at 0x0140
 - These are strong dependencies on the way the software is architected/built
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Model of Dependencies

II. Hardware IP & Processor



- A Processor access several Memory Banks
- Each Memory Bank is accessed at a single Base Address
- A Memory Bank is made of several Memory Cells
- A Register is a Memory Cell
- A HW IP exports several Memory Cells

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Summary of SW/SW dependencies

- Automatic assembly is based on structural dependencies
 - Not easy: Move progressively from simple to more complex cases
 - Otherwise the README file will strike back
- Structural dependencies of HdS are
 - Not only about dependencies over HW IPs
 - But also about deeper SW dependencies
 - Processors
 - Compilers ABI
 - Memory map
 - Boot ordering

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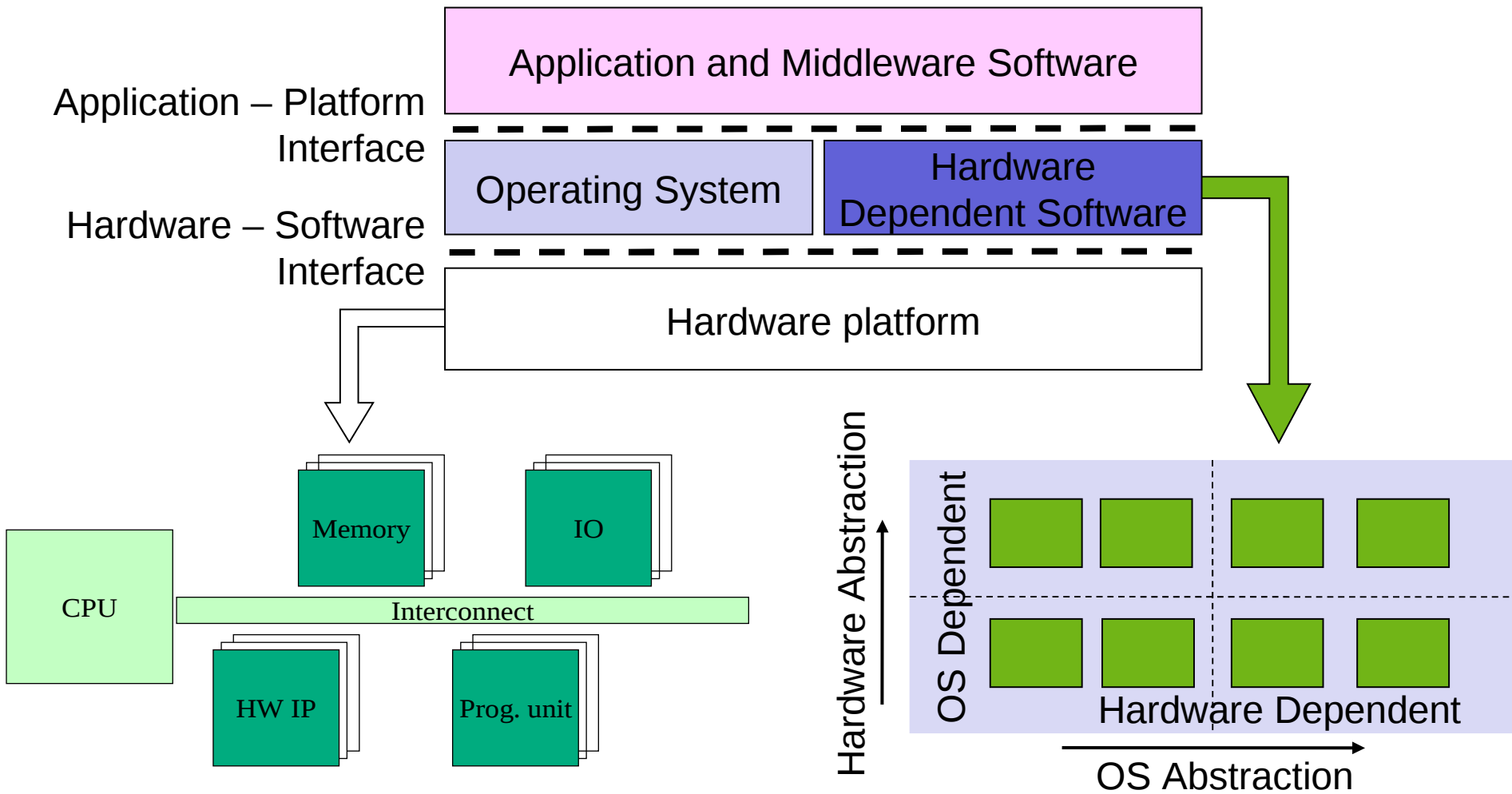
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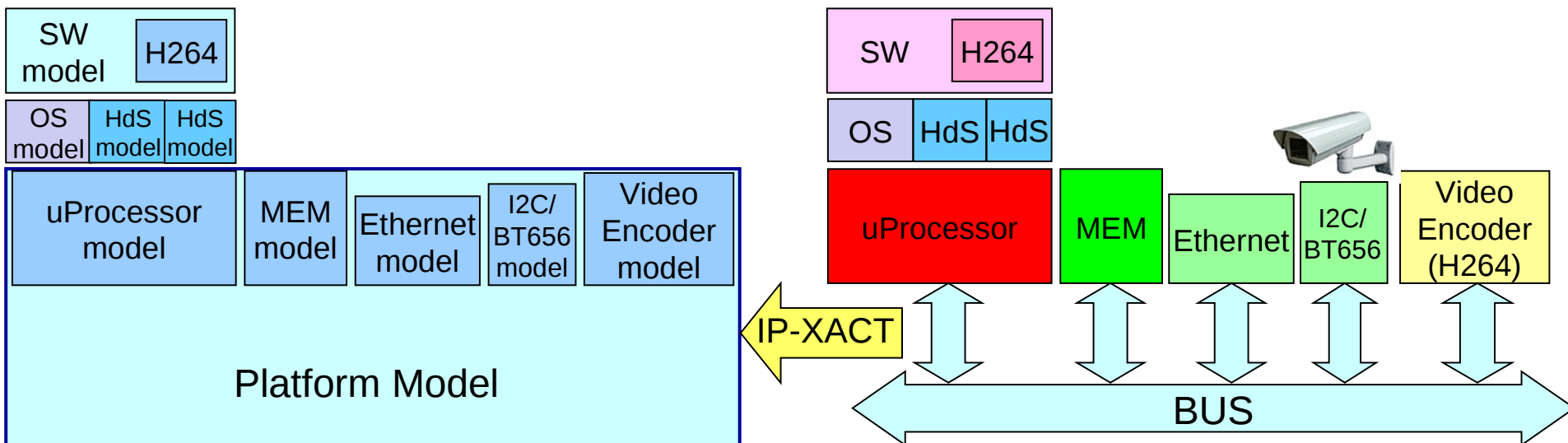
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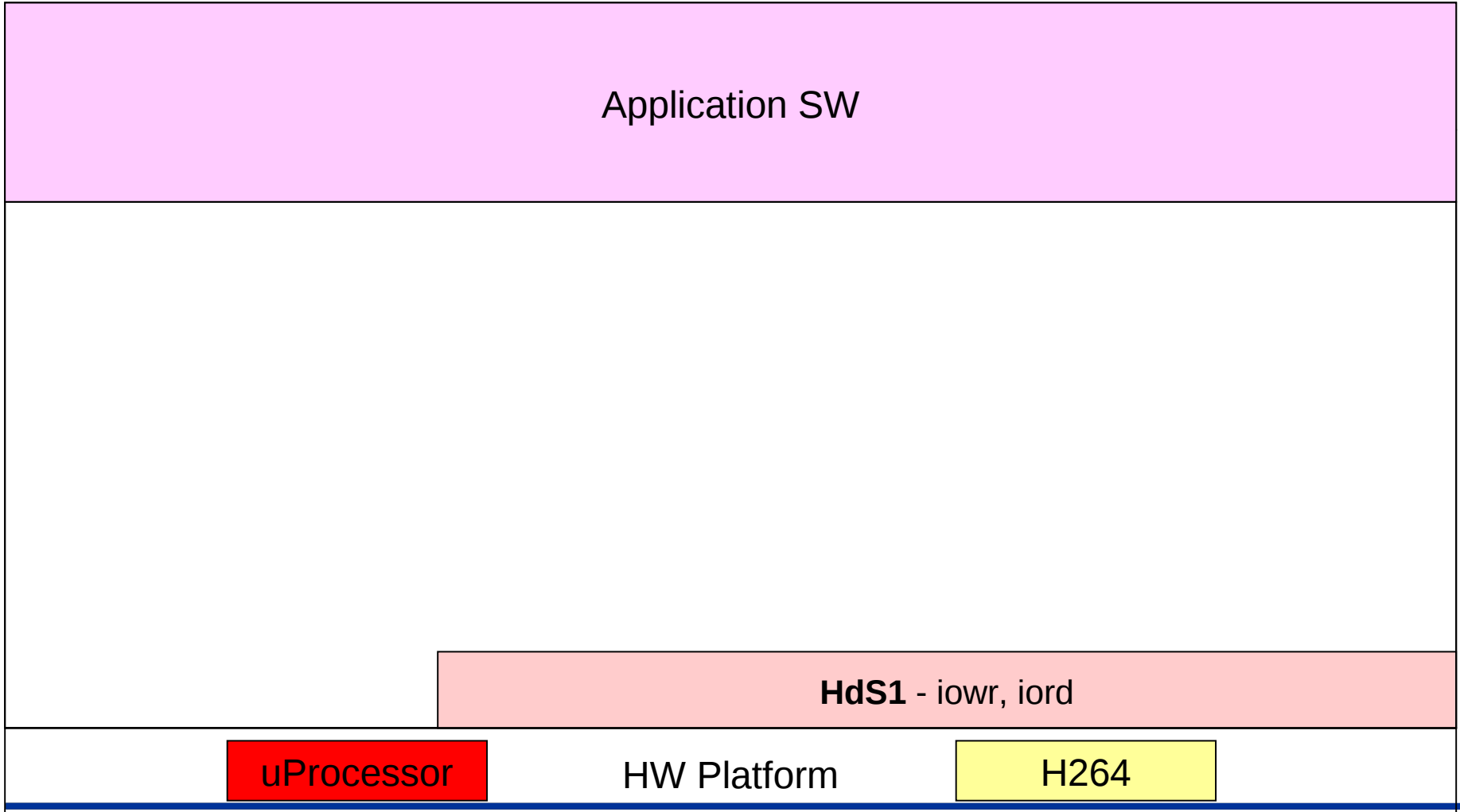


- More complex architectures
 - More complex HdS
 - More complex HdS models
 - Increased dependencies w.r.t. OS, HW, μ Processor...
 - Current ‘hand-written’ approach no longer valid

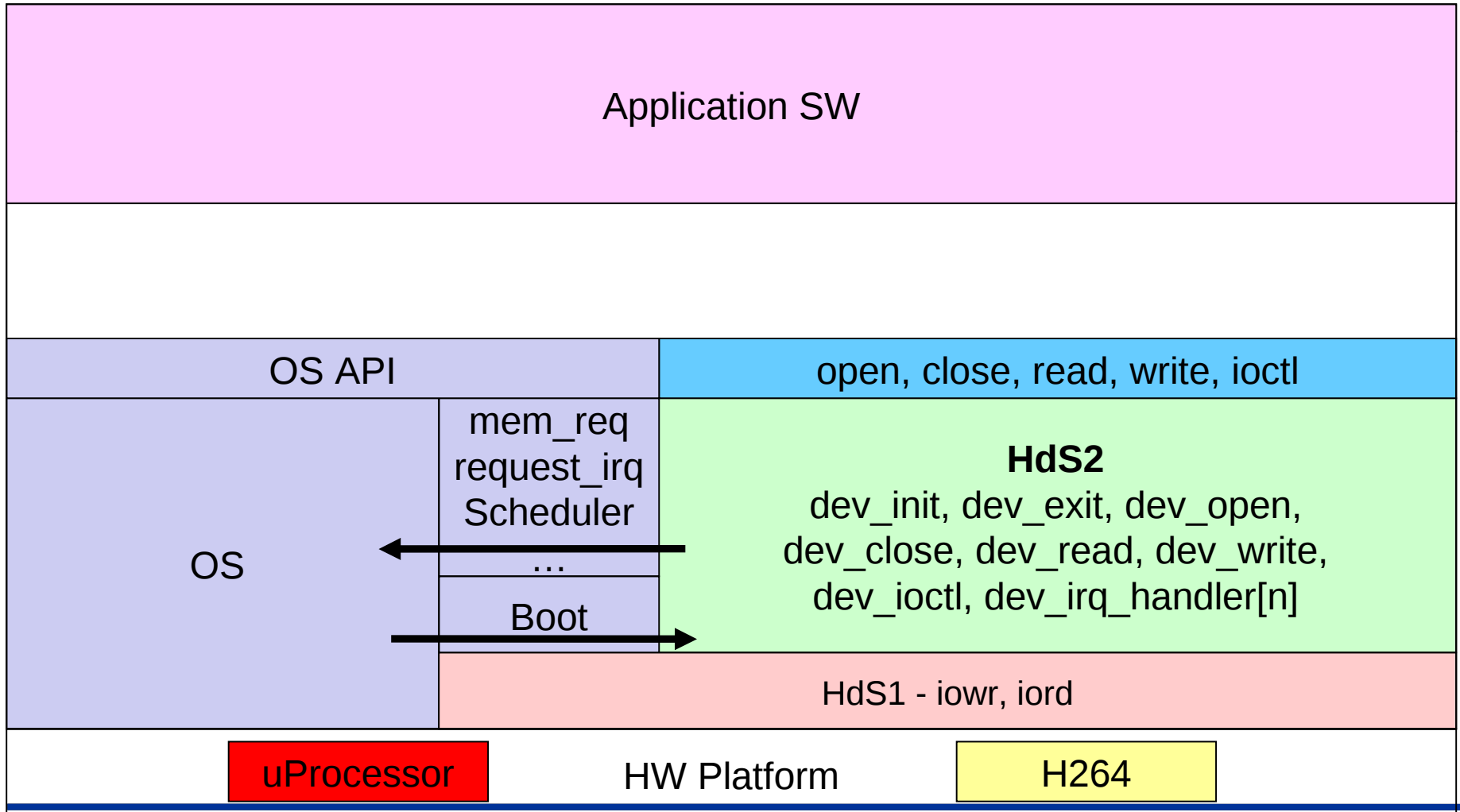
An structured approach

- Objectives
 - Automate the HdS generation
 - Automate the HdS model generation
 - Capsulate dependencies w.r.t. OS, HW, μ Processor...

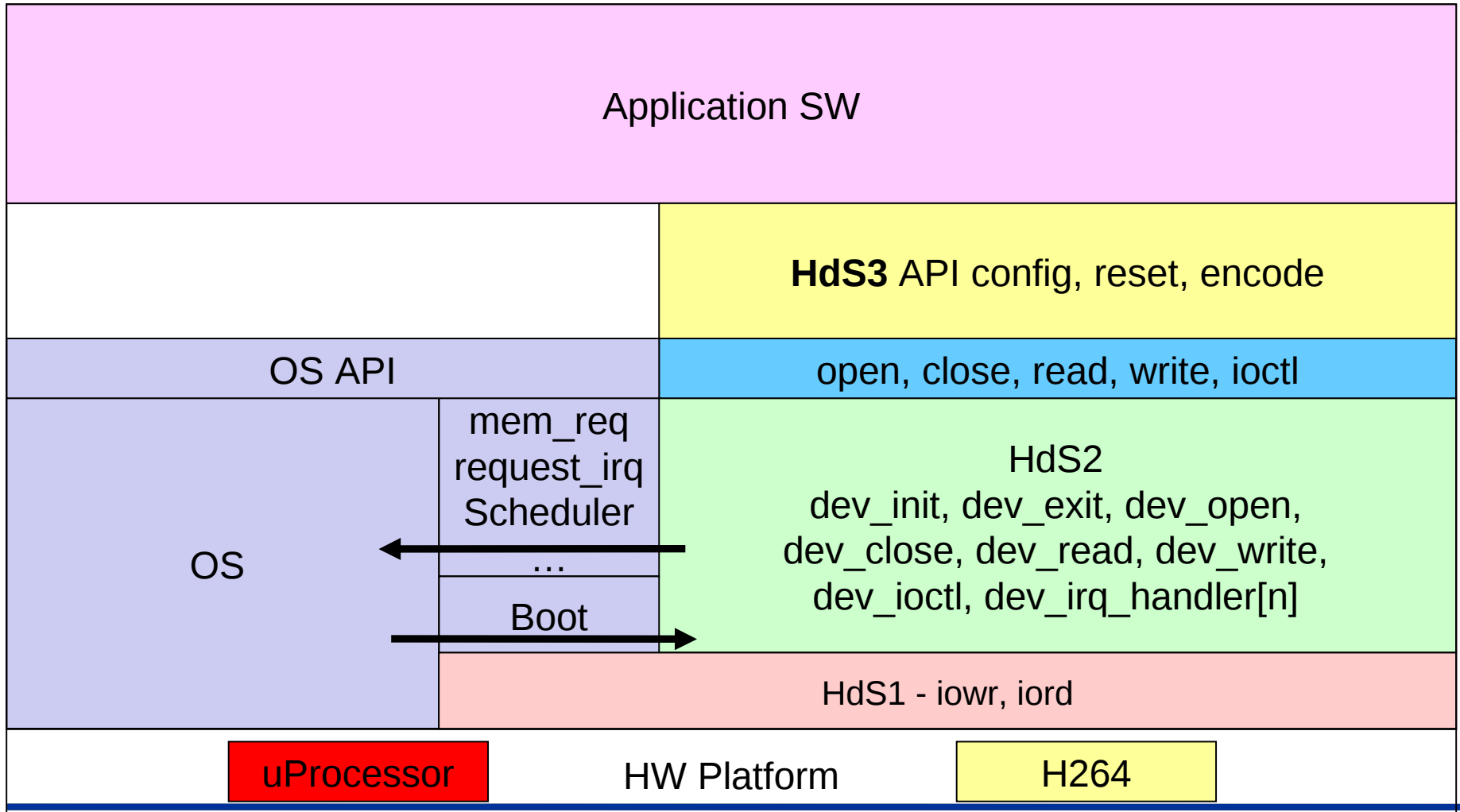




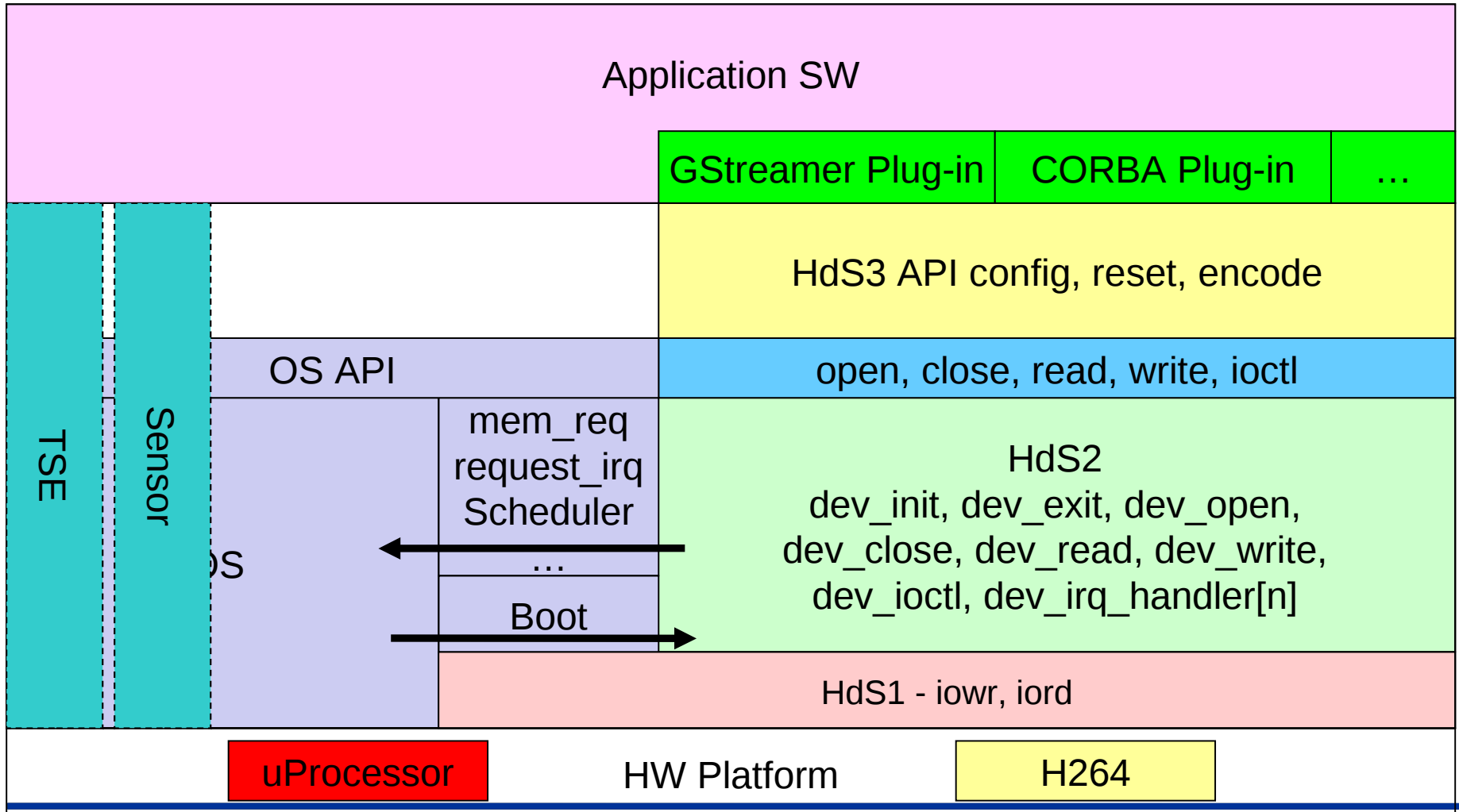
- Depends on:
 - Specific HW (H.264 HW component)
 - uProcessor (only if assembler code)
 - OS (through its register access functions)
- Objectives:
 - Basic functionality
 - Support low-level accesses to HW platform
 - iord → read request
 - iowr → write request



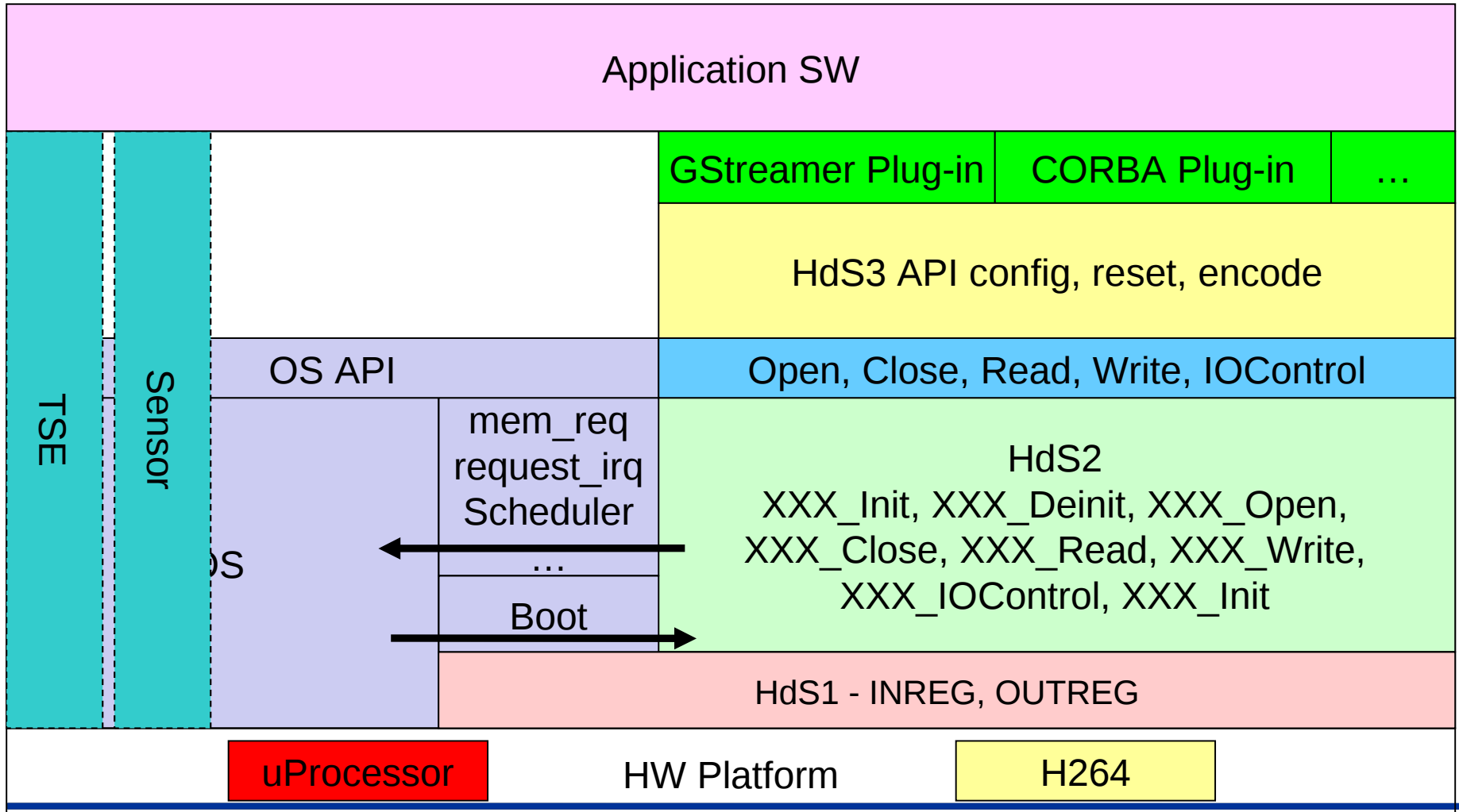
- Depends on:
 - OS/RTOS (Linux in example)
 - Specific HW (H.264 HW component)
 - HdS1
- Objectives:
 - Establishes communication with OS/RTOS
 - Defines OS/RTOS specific access functions
 - Provides services through OS/RTOS general access functions



- Depends on:
 - Specific HW (H.264 HW component)
 - HdS2
- Objectives:
 - Defines specific functions according to HW capabilities
 - Encapsulate complex functionality in specific functions
 - Provides abstraction from HW platform



- Depends on:
 - HW platform capabilities
 - HdS3
- Objectives:
 - Adapts HdS3 to libraries and specific software
 - Allows to merge HW platform capabilities
 - In example: camera with H.264 video-encoded streaming
 - Sensor + H.264 encoder + TSE
 - Provides full abstraction from HW platform
 - Only performance-dependent



HdS Stack Conclusions

- The HdS structured approach
 - Identification of the different components
 - Maximization of the reusability
- OS
 - Linux & WinCE are very similar
 - Opportunities for HdS standardization
 - Facilitates the development of tools
 - Simulation,
 - Synthesis,
 - Verification, ...

- IP-XACT
 - Current IP-XACT is the “level 0” layer
 - Only describes the HW platform
 - SoftSoC opens IP-XACT to “n” levels of abstraction
 - Easy identification of IP services at different levels
 - Higher level → less knowledge of concrete services

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Extensions in IP-XACT for HDS

- New schema
 - Structured and standardized electronic documentation dedicated to HDS structure (layers)
 - in relation with HW platform in IP-XACT schema (level 0)
 - Description of SW blocks and structure assembly
 - Dependencies with HW processors, compilers, OS, etc.
 - Interfaces: SW-SW, inter layers, SW-HW + definition of services
 - Specificities for HDS1, 2, 3, middleware ?
 - Views for several implementations
 - Extensions of existing IP-XACT
 - Reference to several drivers
 - Description of performances (power, timing)
 - Provided services toward the SW layers (list of standard services?)
-

Solutions and tooling for HDS

Design environment (base on IP-XACT)

- SW architecture assembly (hierarchical) in a reuse and multi site context
- Manage though a comon cockpit the heterogenity of tools, methods and languages
- Automate the HW/SW codesign and mapping

Tools and engines

- Import/export to/from IP-XACT
 - UML description of HDL layers
 - Doc generation
 - Design Verification
 - Required services available on HW platform?
 - Verify the access of HW registers by SW (though buses, bridges...)
 - Etc...
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